

Matthew Strong

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EDUCATION

Stanford University

PhD in Computer Science, Robotics/AI. Advisor: Monroe Kennedy, Jeannette Bohg

Stanford, CA

Sep 2023 – present

University of Colorado Boulder

Bachelor of Science in Computer Science, Chinese Minor, 4.00 GPA

Boulder, CO

Aug. 2017 – May 2021

EXPERIENCE

Robotics/AI PhD Researcher, ARMLab - Stanford University

ARMLab, Advised by Monroe Kennedy and Jeannette Bohg

September 2023 – present

Stanford, CA

- Research on dexterous robot manipulation.
- Building on top of the DenseTact sensor for perception and autonomy.
- Integrated visual-tactile data into 3D Gaussian Splatting.

Software Engineer - Customer Experience Platform (CXP)

Microsoft

September 2021 – August 2023

Redmond, WA

- AI-based solutions to improve the customer journey experience.
- Designed, developed, and deployed the consent for channel optimization feature for CXP.
- Developed Holdout for A/B test experimentation.

Undergraduate Researcher - CU Boulder SBS Lab

Sustainable Buildings and Systems Lab, Advised by Wangda Zuo

January 2018 – present

Boulder, CO

- Automated energy building simulation pipeline for energy outputs of building models in different climate zones.
- Building energy prediction models with Generative Adversarial Networks.
- Core contributor of an open source release of 500+ building models collaboration with NREL and Oak Ridge.

Undergraduate Researcher - HIRO Group

HIRO (Human Interaction and RObotics Group) Group, Advised by Alessandro Roncone

January 2020 – September 2021

Boulder, CO

- Novel kinematic calibration algorithm to estimate the pose of a novel sensor unit on a robot manipulator. Validated on a real robot control example.
- Proposed a framework for bridging the gap between avoidance and contact, informed by onboard sensors for collaborative robotics.
- Constructed an effective method for probabilistic fusion of external depth data and onboard proximity data to reduce occlusions in a robot's nearby space.

Software Engineer Intern - Journey Optimization using RL

Microsoft, Customer Experience Platform (CXP)

May 2020 – August 2020

Remote - Broomfield, CO

- Deployed a real-time analytics service for retrieving customer data.
- Designed and developed a feature from scratch called journey optimization, which intelligently guides a customer through the "customer journey", using reinforcement learning.

CTO and Co-Founder - Udana Systems

Udana Systems

February 2018 – May 2020

Boulder, CO

- Co-Founded company targeted towards drone delivery for small to medium sized businesses.
- Designed and developed robotics tech stack, using ROS, MavROS, Gazebo, PyTorch, and more.
- Developed machine learning pipeline for computer vision based models.

Software Engineer Intern - Global Search

Microsoft, Dynamics 365 for Talent

May 2019 – July 2019

Redmond, WA

- Designed and developed the Global Search feature for Microsoft Dynamics 365 for Talent.
- Worked with .NET, Angular, and XML in order to successfully deploy an end-to-end feature.

PUBLICATIONS

Next Best Sense: Guiding Vision and Touch with FisherRF for 3D Gaussian Splatting
International Conference on Robotics and Automation 2025. Submitted.

Matthew Strong*, Boshu Lei*, Aiden Swann, Wen Jiang, Kostas Daniilidis, Monroe Kennedy III

Touch-GS: Visual-Tactile Supervised 3D Gaussian Splatting

International Conference on Robotics and Systems 2024. Oral.

Aiden Swann*, **Matthew Strong***, Won Kyung Do, Gadiel Sznajer Camps, Mac Schwager, Monroe Kennedy III

SHIRO: Soft Hierarchical Reinforcement Learning

Arxiv.

Kandai Watanabe*, **Matthew Strong***, Omer Eldar

Individualized Empirical Baselines for Evaluating the Energy Performance of Existing Buildings
Science and Technology for the Built Environment.

Yingli Lou, Yunyang Ye, Yizhi Yang, Wangda Zuo, Gang Wang, **Matthew Strong**, Satish Upadhyaya, Chris Payne

Evaluating Performance of Different Generative Adversarial Networks for Large-Scale Building Power Demand Prediction

Energy and Buildings.

Yunyang Ye, **Matthew Strong**, Yingli Lou, Cary Faulkner, Wangda Zuo, Satish Upadhyaya.

Volumetric Data Fusion of External Depth and Onboard Proximity Data For Occluded Space Reduction

4th Workshop on Proximity Perception in Robotics at IROS 2021.

Matthew Strong*, Caleb Escobedo*, Alessandro Roncone.

Contact Anticipation for Physical Human–Robot Interaction with Robotic Manipulators using Onboard Proximity Sensors

International Conference on Robotics and Systems 2021. Oral.

Caleb Escobedo, **Matthew Strong**, Mary West, Ander Aramburu, Alessandro Roncone

Self-Contained Kinematic Calibration of a Novel Whole-Body Artificial Skin for Collaborative Robotics

International Conference on Robotics and Systems 2021. Oral.

Kandai Watanabe, **Matthew Strong**, Mary West, Caleb Escobedo, Ander Aramburu, Krishna Chaitanya, Alessandro Roncone.

Enabling Close Proximity Human Robot Collaboration via Distributed, Self-Calibrating Robotic Skin

BS Thesis at CU Boulder. Committee: Alessandro Roncone, Bradley Hayes, Christoffer Heckman
Matthew Strong.

Development of New Baseline Models for U.S. Medium Office Buildings Based on Commercial Buildings Energy Consumption Survey Data

Science and Technology for the Built Environment Volume 26, 2020.

Yunyang Ye, Yingli Lou, **Matthew Strong**, Satish Upadhyaya, Gang Wang, Wangda Zuo.

SERVICE/LEADERSHIP

Microsoft BAP Early-in-Career	2023
<ul style="list-style-type: none">One of the founding members of a newly revamped Early-in-Career group.Leader of the Dynamics 365 Early-in-Career groupPlanned events, including single-handedly starting a AMA with the Corporate Vice President of the org.	
HackCU	August 2018 – May 2021
<ul style="list-style-type: none">Led HackCU's tech team, organizing the largest hackathon in the Rocky Mountain region.Managed whole tech stack during 500+ person hackathon.Developed hacker sites and APIs accessed by thousands of people across the nation and globe.Handled 1000+ hacker applications.	
Slingshot Mentor and Founding Member	June 2020 – September 2021
<ul style="list-style-type: none">Served as a founding member for students from top high schools interested in CS at Slingshot, a Techstars-backed startup co-founded by students from top tech companies.Organized learning sessions about robotics, research, and machine learning for high school students.Onboarded startups out of Y-Combinator, Techstars, Berkeley, Stanford, and more.	
Discrete Structures Tutor	January 2019 – May 2019
<ul style="list-style-type: none">Mentored student in discrete structures.Set homework and test-prep deadlines, and prepared practice problems.	
SASE (Society of Asian Scientists and Engineers) Leadership	January 2018 – May 2018
<ul style="list-style-type: none">Served as Co-Marketing Director and managed social media pages.	

AWARDS

National Science Foundation Graduate Research Fellowship	April 2024
<ul style="list-style-type: none">Received prestigious NSF GRFP for my PhD studies at Stanford.	
Microsoft Special Stock Award	July 2023
<ul style="list-style-type: none">The most prestigious bonus given to employees at Microsoft. Only a few individuals were nominated out of the 200+ employees in my organization.	
RSS Inclusion Fellow	June 2021
<ul style="list-style-type: none">Accepted as an RSS (Robotics: Science and Systems) Inclusion Fellow, an expenses-paid program for upcoming robotics researchers attending RSS.	
Chancellor's Recognition Award	May 2021
<ul style="list-style-type: none">An award given to students that maintain a 4.0 GPA throughout all of college.	
Active Learning Award	April 2021
<ul style="list-style-type: none">Award given to outstanding students in service, professional, and research experiences.	
College of Arts and Sciences: Class of 2021 Amazing Student	April 2021
<ul style="list-style-type: none">For my minor in Chinese, I received an outstanding student award for the Class of 2021 in the College of Arts of Arts and Sciences (1 of 30 out of 4500+ students).	
College of Engineering Research Award	April 2021
<ul style="list-style-type: none">Only one other CS student from CU has received this award in its 20+ year history.	
CRA Outstanding Undergraduate Researchers 2021 – Honorable Mention	December 2020
<ul style="list-style-type: none">The most prestigious award for CS undergraduate researchers in North America.	

UROP Research Grant: Null Space Control for Collaborative Robotics	August 2020 – August 2021
• Received \$1500 research grant from CU Boulder's Undergraduate Research Opportunities Program (UROP) to perform research on null space control.	
Sewall Scholar	August 2017 – May 2021
• The top merit scholarship at CU Boulder.	
Engineering Merit Scholarship	August 2017 – May 2021
• Received based on high school academic performance.	
BOLD Scholarship	August 2017 – May 2021
• Received diversity scholarship based on high school achievement.	
National Merit Scholar	August 2017
• Selected to receive National Merit Scholarship on basis of outstanding high school achievement.	
• Given to <1% of high school seniors in the US.	

MEMBERSHIP

Microsoft BAP EIC Group	March 2022 – August 2023
Colorado Data Science Team	August 2019 – December 2020
SHPE (Society of Hispanic Professional Engineers)	August 2019 – May 2021
SASE (Society of Asian Scientists and Engineers)	August 2017 – August 2019

INVITED TALKS

HackCU Workshop Invited Speaker: An Introduction to AI	March 2024
• Gave a talk on an introduction to AI at HackCU.	
HackCU Workshop Invited Speaker: A Gentler Introduction to Robotics	March 2022
• Invited to conduct a workshop on how to get started with algorithm robotics at HackCU.	
Invited Speaker at the PhD Forum: 4th Workshop on Proximity Perception in Robotics	August 2021
• Only undergraduate invited to speak at the forum.	
Slingshot Interview Series: Getting Involved in Robotics	August 2021
• Invited by Techstars-backed startup to be interviewed on my experience with robotics, how I improved, and what others can learn from me.	

REVIEWER

IEEE International Conference on Robotics and Automation (ICRA)	2023, 2025
IEEE Robotics and Automation Letters (RA-L)	2023, 2024
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	2022, 2024